

Robotic Lunch September 2024

DR. TECHN. DI MUGDIM BUBLIN

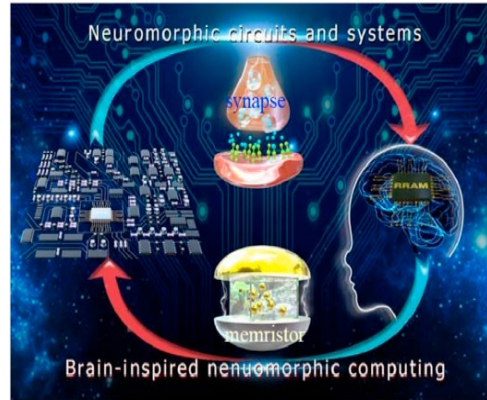
Neuromorphic Robotics



Brain-inspired Neuromorphic Computing

Digital computing technologies **challenges:**

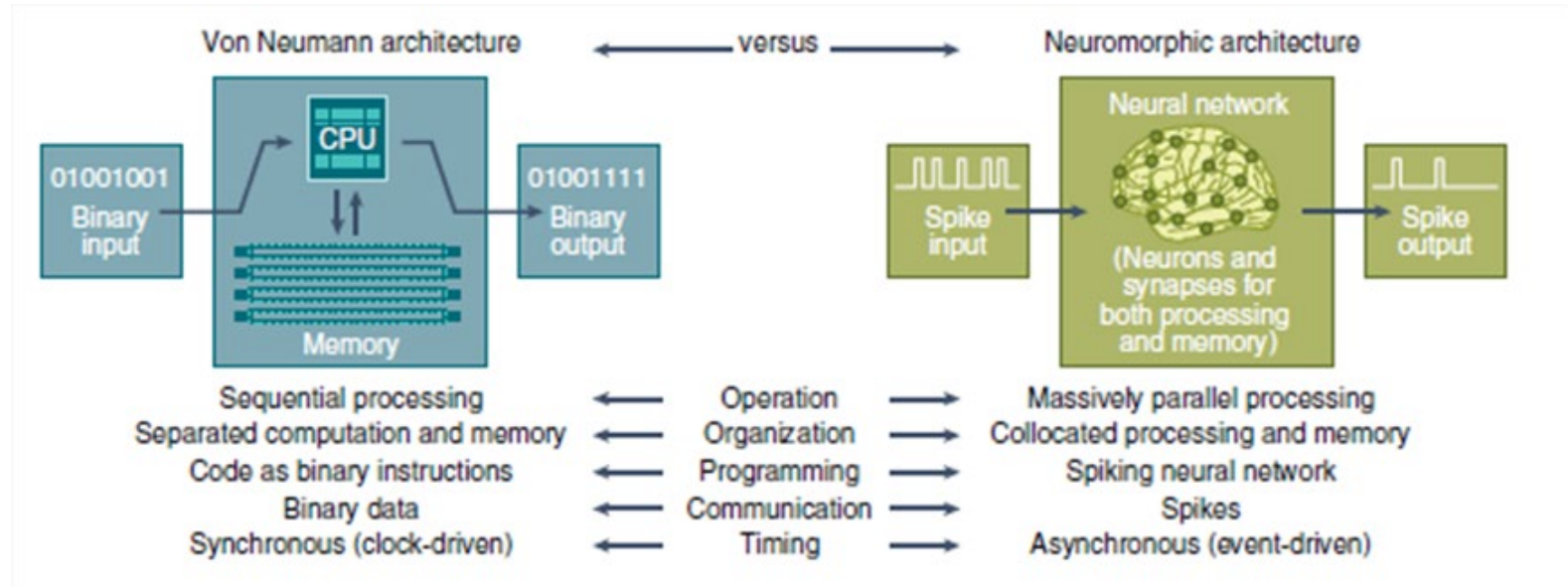
- **Energy footprint:**
classical Deep Learning needs about 20 MW
- **Toxicwaste**
- Limits of **miniaturization**
- Vulnerabilities of ever-growing software **complexity**



Brain-inspired Neuromorphic Computing improves:

- **Energy efficiency**, our brain needs about 20 W
 - **Noise robustness**
 - **Adaptability**
 - **Safety**
 - **Costs**
- => **New Computing Paradigm**

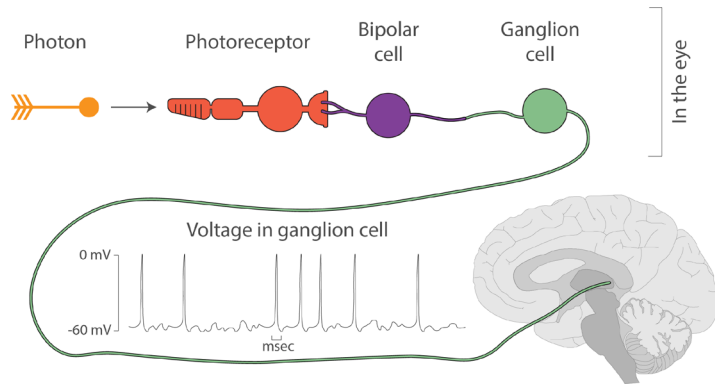
Traditional vs. Neuromorphic Architecture



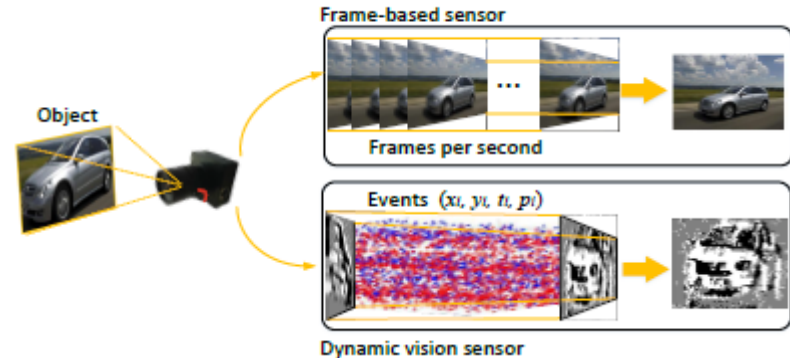
Schuman, Catherine D., et al. "Opportunities for neuromorphic computing algorithms and applications." *Nature Computational Science* 2.1 (2022): 10-19.

Event Based Processing

- The standard camera outputs frames at a **fixed rate**, thus sending **redundant information when there is no motion** in the scene
- Event cameras respond to pixel-level **brightness changes** with **microsecond latency**



Human vision:
<https://i-kh.net/2021/03/01/human-vision-system-an-overview/>

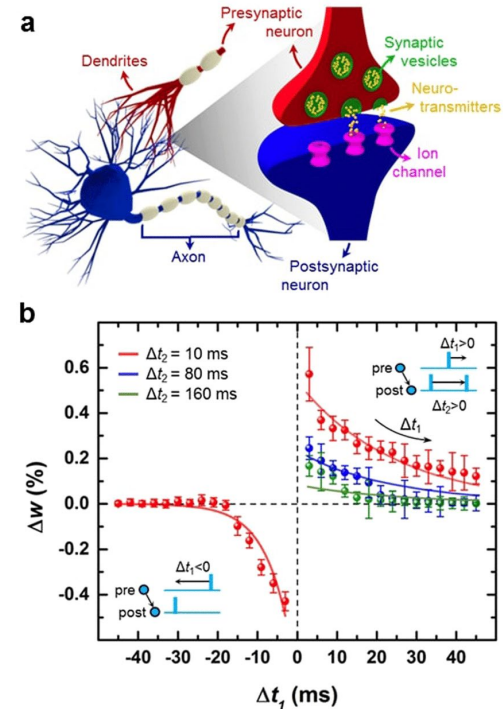


Gao, Shan, et al. "An end-to-end broad learning system for event-based object classification." IEEE Access 8 (2020): 45974-45984.

Collocated Processing and Memory

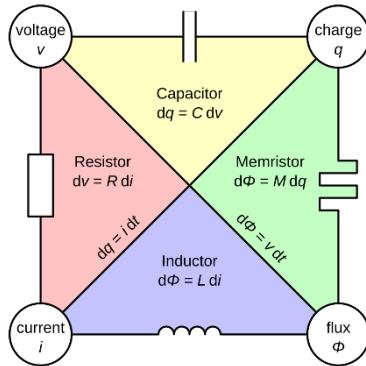
- Connections between nerve cells (**Synapses**) serve as **both processing and memory elements**
- **Spike-timing-dependent plasticity (STDP)** is a biological inspired learning that adjusts the strength of connections between neurons in the brain
- Only **local information** (pre – and post-times) are used
- **Backpropagation** requires **global information** (cost-function gradients)

Ahmed, Taimur, et al. "Time and rate dependent synaptic learning in neuromimicking resistive memories." Scientific Reports 9.1 (2019): 15404.

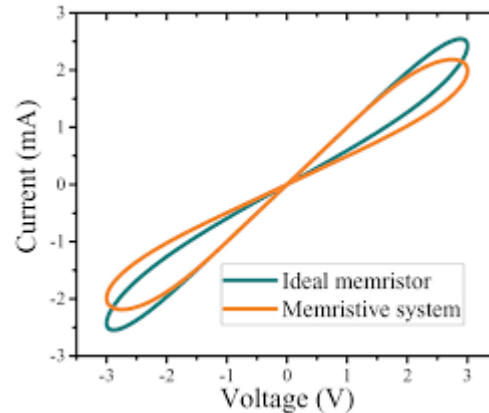


Memory Implementation - Memristors

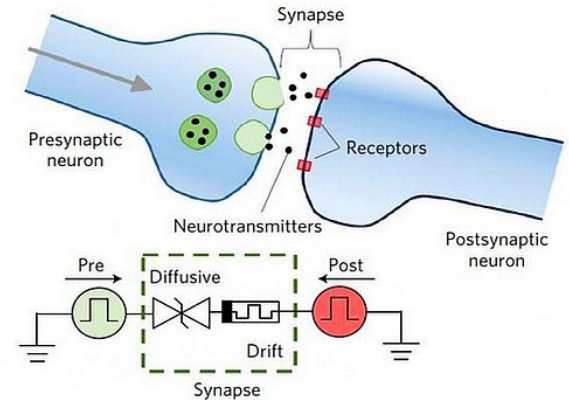
- A **memristor** (/ˈmɛm.rɪ.stər/; a portmanteau of memory resistor) is a non-linear two-terminal electrical component **whose resistance depends on the magnitude, direction, and duration of the applied voltage.**



Chua, Leon. "Memristor-the missing circuit element." IEEE Transactions on circuit theory 18.5 (1971): 507-519.

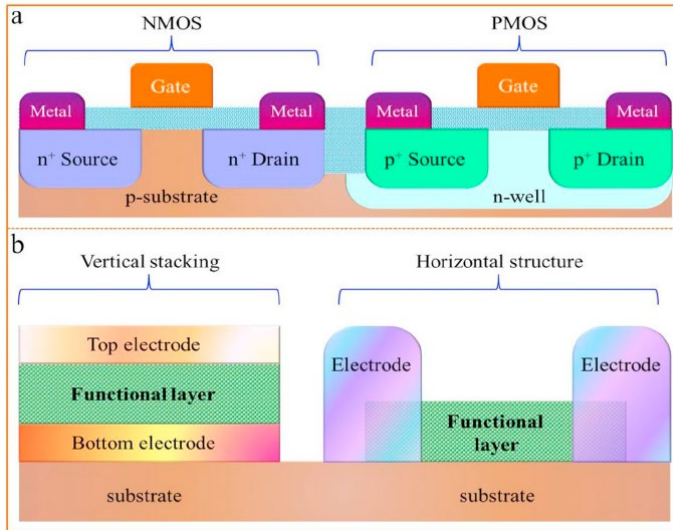


- Memristor can actually express **both long-term and short-term plasticities in synapses.**

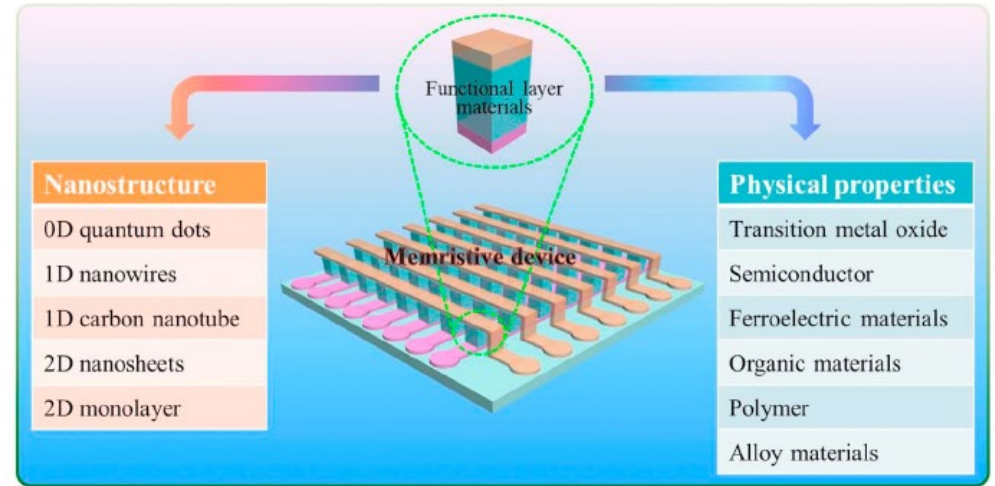


Cai, Weiran, and Ronald Tetzlaff. "Synapse as a Memristor." Handbook of Memristor Networks (2019): 351-367.

Memristor Implementations



(a) Structures of CMOS devices
(b) Structures of memristive devices

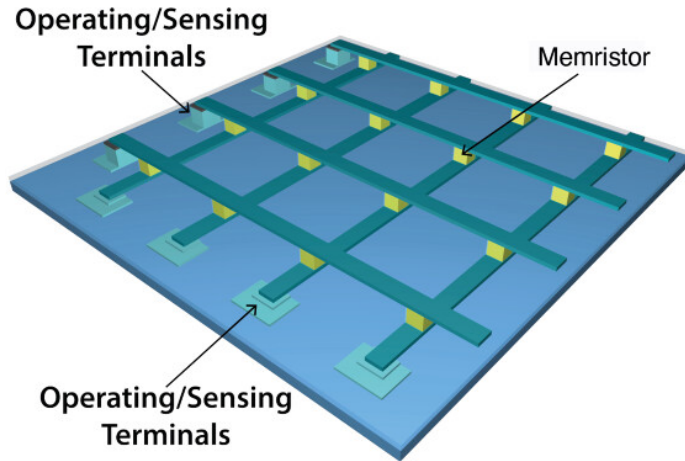


Sun, Bai, et al. "Synaptic devices based neuromorphic computing applications in artificial intelligence." *Materials Today Physics* 18 (2021): 100393.

In-Memory Computing with Memristors

Simple implementation of Matrix – Vector Product:

(a) **Memristor Crossbar Array**

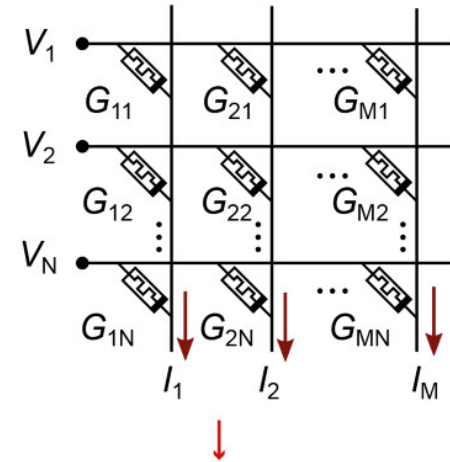


(b)

Input: Multiplication vector
is defined by voltage vector \underline{V}

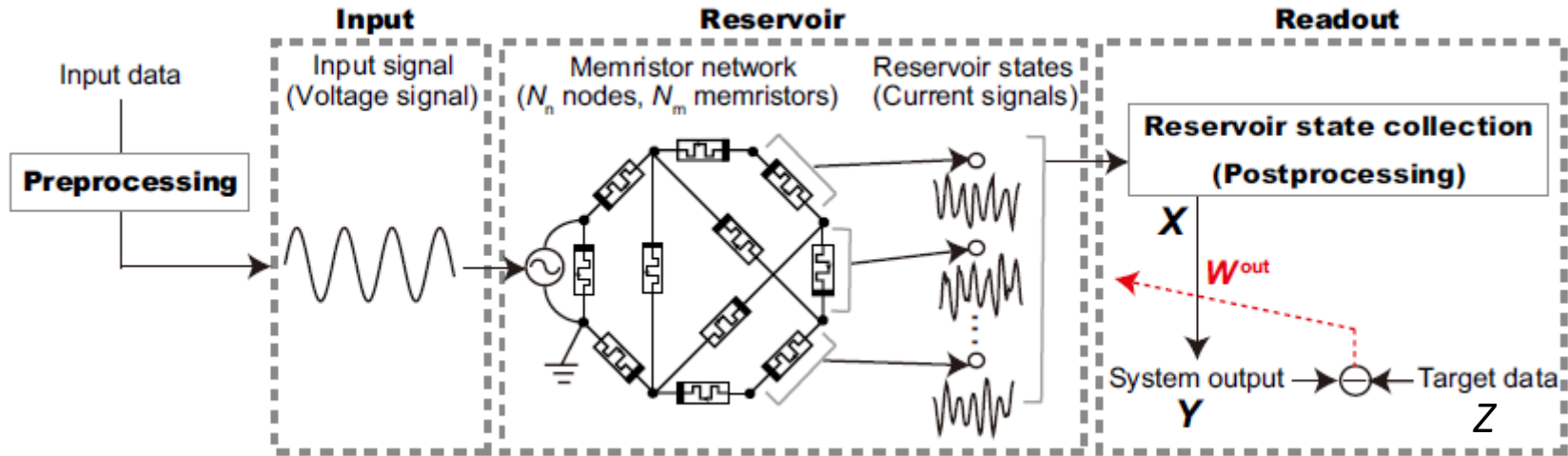
$$\underline{I} = \underline{G} \underline{V}$$

Input: Multiplication matrix, G ,
is mapped onto memristor crossbar array



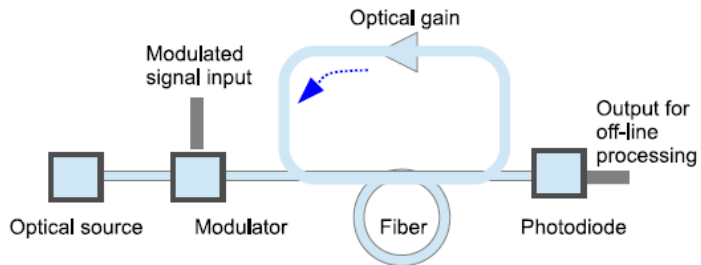
Output: Current vector \underline{I} represents a
vector-matrix product

Random Memristor Network as a Reservoir



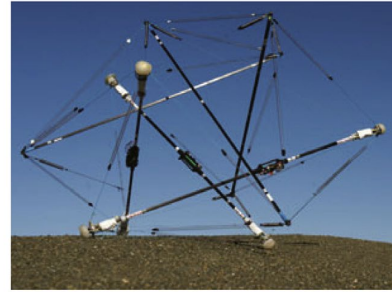
Reservoir Examples

Fluidic RC where the reservoir is the water in a bucket

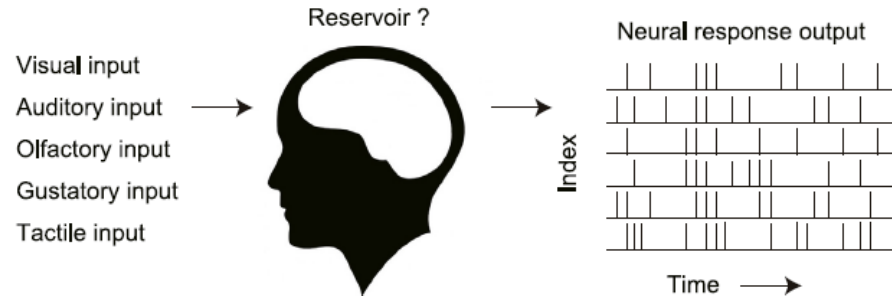
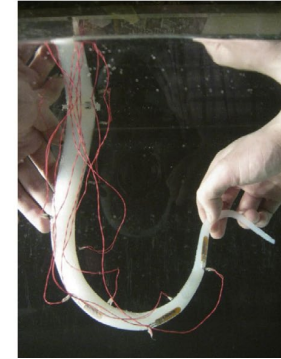


(a) A tensegrity structure-based reservoir (b) A reservoir based on a soft octopus robot

(a)



(b)



Tanaka, Gouhei, et al. "Recent advances in physical reservoir computing: A review." *Neural Networks* 115 (2019): 100-123.



Safety & Security Considerations

- **Security**

More difficult to access and change analog hardware like Memristors or Reservoir over internet

- **Safety**

For analog systems it is possible to use continuity properties when pondering system behavior in different points of their state space. If a system exhibits intended behavior in a situation A and in a related situation B, it can be argued that it will show intended behavior also when $C = \alpha A + (1 - \alpha) B$, where $0 < \alpha < 1$ ¹

¹Wahlström, Björn. "Differences between analog and digital I&C." Proceedings of the 9th International Conference on Nuclear Plant Instrumentation, Control & Human-Machine Interface Technologies (NPIC & HMIT 2015). 2015.

Total Turing Test

- Some modern AI systems like ChatGPT can already pass classical Turing Test?
- Turing viewed the physical simulation of a person as unnecessary to demonstrate intelligence.
- Modern robots are much further away from human physical capabilities than ChatGPT from human cognitive capabilities.
- Other researchers have proposed a **total Turing test**, which requires **interaction with objects and people** in the real world:
 - **Robotics** to manipulate objects and move about

Physical Embedding

Studying brain not enough, we need:

- **Embedding** of brain into organism
- **Interaction** with environment
- Exploit the “intelligence” of underlying **physics and materials**

Bio-Inspired Robotics

Same Fundamental Principles valid in Design of **Biological** and **Technical** Systems:

- Distributed
- Hierarchical
- Adaptive
- Feedback
- Simple rules leads to complex behaviour
- Learning
- Self-organized
- Emergent
- Stygmergy
- Redundancy
- ...





Principles of Neuromorphic Robotics

- Communicate only if something changes => Spiking neurons
- Use local information for local learning => STDP learning rule
- Use available physics as much as possible => Reservoir
- Exploit “physical body intelligence” => Embodiment
- Distributed control => Self Organization
- Complex behavior from simple rules => Emergence

Highly interdisciplinary endeavor!



**Thank You For Your
Attention**